

Fabian Peddinghaus

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EDUCATION

Stanford University <i>Visiting Student Researcher with Subhasish Mitra and Priyanka Raina</i> <i>Compilation flow for deep learning accelerator</i>	Sep. 2022 – Dec. 2022 <i>Stanford, United States</i>
Technical University of Munich <i>M.Sc. Electrical and Computer Engineering, current grade 1.0, top 2%</i> <i>Focus on computer architecture and machine learning</i>	Apr. 2021 – Feb. 2023 <i>Munich, Germany</i>
Technical University of Berlin <i>B.Sc. Computer Engineering, grade 1.3, top of class</i> <i>Dissertation on spectrum sensing for nanosatellites</i>	Oct. 2017 – Mar. 2021 <i>Berlin, Germany</i>
German Academic Scholarship Foundation <i>Scholarship, awarded for outstanding academic potential to 0.5% of students in Germany</i>	Feb. 2020 – Present

EXPERIENCE

Graduate Research Assistant <i>TU Munich, Department of Electronic Design Automation</i> <ul style="list-style-type: none">Ported ARM's CMSIS-NN to RISC-V using the Vector V and Packed P extensionsIntegration of RISC-V Vector compute kernels with TensorFlow and TVMWorked on embedded ML-based signal and speech processingTA for course: Embedded System Design for Machine LearningTA for course: Embedded Systems and Security	Oct. 2021 – Sep. 2022 <i>Munich, Germany</i>
Undergraduate Research Assistant <i>TU Berlin, Department of Flight Mechanics and Flight Control</i> <ul style="list-style-type: none">Developed a novel guidance and control system (hard- and software) using distributed wireless control algorithmsConducted research into state estimation and real-time controlTA for course: Aviation and flight control software	Oct. 2018 – Mar. 2021 <i>Berlin, Germany</i>
Working Student Software Developer <i>HeyCar</i> <ul style="list-style-type: none">Developed IoT customer endpoint with database integration	Apr. 2018 – Aug. 2018 <i>Berlin, Germany</i>
Embedded Software Developer <i>CooperCopter GmbH</i> <ul style="list-style-type: none">Worked on software stack for novel drone propulsion system (2nd at German Aviation Innovation Award, 2017)Developed flight control and power management solutions for unmanned aerial systems	May 2013 – Sep. 2017 <i>Hamburg, Germany</i>

PROJECTS

IFSys Student Initiative <i>Technical lead for university student project</i> <ul style="list-style-type: none">Development of unmanned aerial system for search and rescueIn-house hard- and software developmentPresentations, public relations, exhibitions, and events	Oct. 2018 – Present
Biped Robot <i>Developed as a side project</i> <ul style="list-style-type: none">Wrote 12 DOF humanoid estimation and control algorithmsLow-level hardware driver for IMUs and servo motors	Feb. 2018 – Apr. 2018

TECHNICAL SKILLS

Languages: C, Python, C++, Assembly (RISC-V, ARM, MIPS), VHDL, Java, Haskell
Libraries and Platforms: ONNX, TensorFlow Lite, PyTorch, Vector intrinsics (x86 and RISC-V), TVM, NumPy, SciPy, CUDA, OpenCL, OpenMP, PyWavelets
Developer Tools: CMake, Make, Git, Unity, Google Test, Bash, Linux